

Meaning of Stokes Theorem:

Stokes Theorem:

$$\iint_S \text{Curl } \vec{F} \cdot \vec{n} \, dS = \int_C \vec{F} \cdot \vec{T} \, ds$$

Flux of the Curl \vec{F} thru S

line integral around boundary

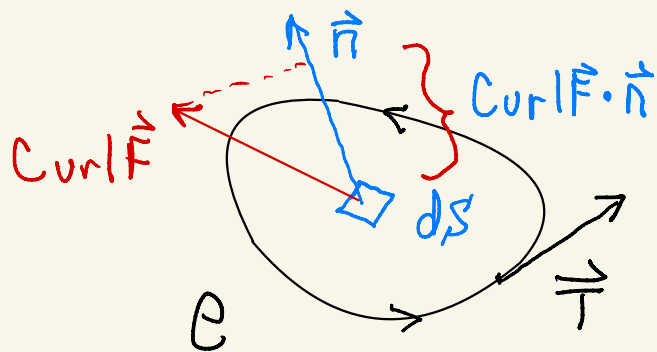
Example: Verify

Stokes Theorem in

case $S =$ hemisphere

$$x^2 + y^2 + z^2 = 9, \quad z \geq 0$$

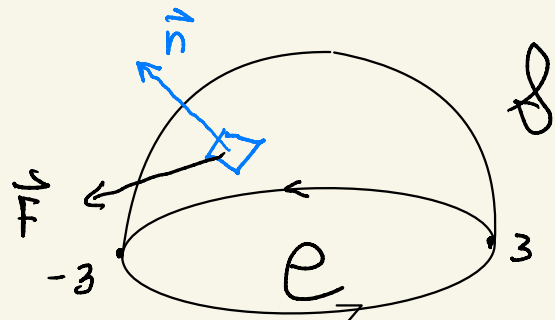
$$\vec{F} = y \hat{i} - x \hat{j}$$



Soln: The boundary Curve for the hemisphere

$$is: C = x^2 + y^2 = 9$$

• First we calculate RHS!



$$\int_C \vec{F} \cdot \vec{T} \, ds = \int_C M dx + N dy = \int_0^{2\pi} 3y(-\sin t) - 3x \cos t \, dt$$

$t = \theta$
 $x = 3 \cos t$ $y = 3 \sin t$
 $0 \leq t \leq 2\pi$

$dx = -3 \sin t \, dt$ $3 \sin t$ $-3 \cos t$
 $dy = 3 \cos t \, dt$

$$= 9 \int_0^{2\pi} -\sin^2 t - \cos^2 t \, dt = -9 \cdot 2\pi = \boxed{-18\pi}$$

• Now calculate LHS: $\iint_S \text{Curl } \vec{F} \cdot \vec{n} \, dS$

(2)

$$\text{Curl } \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \partial_x & \partial_y & \partial_z \\ y & -x & 0 \end{vmatrix} = \hat{k}(-1-1) = -2\hat{k}$$

$$\vec{r}(x, y) = (x, y, \sqrt{9-x^2-y^2})$$

$$\vec{n} = \frac{x\hat{i} + y\hat{j} + z\hat{k}}{\sqrt{x^2 + y^2 + z^2}} = \frac{x\hat{i} + y\hat{j} + z\hat{k}}{3}$$

because S is on sphere

$$\text{Curl } \vec{F} \cdot \vec{n} = (-2\hat{k}) \cdot (x\hat{i} + y\hat{j} + z\hat{k}) \frac{1}{3} = -\frac{2}{3}z$$

Spherical coordinates: $u = \phi, v = \theta$

$$\vec{r}(\phi, \theta) = 3(\cos\theta \sin\phi, \sin\theta \sin\phi, \cos\phi)$$

We have: $A = |\vec{r}_\phi \times \vec{r}_\theta| = 3^2 \sin\phi$ (From map problem - or just compute)

$$\iint_S \text{Curl } \vec{F} \cdot \vec{n} \, dS = \iint_D -\frac{2}{3}z \, dS = \int_0^{\pi/2} \int_0^{2\pi} -\frac{2}{3}z \cdot 3^2 \sin\phi \, d\theta \, d\phi$$

$\uparrow 3\cos\phi$

$$= -\frac{2}{3} \cdot 3^3 (2\pi) \int_0^{\pi/2} \cos\phi \sin\phi \, d\phi = -36\pi \left[\frac{\sin^2\phi}{2} \right]_0^{\pi/2} = -18\pi$$

$u = \sin\phi$
 $du = \cos\phi \, d\phi$

(3)

Example (2) Use Stokes to obtain the correct interpretation of $\text{Curl } \vec{F}$ as "circulation per area in \vec{F} "

Soln: Let \vec{F} be a vector field. Recall that

$\oint_C \vec{F} \cdot \vec{T} \, ds$ is the "circulation in \vec{F} around C "

because it measures the component of \vec{F} tangent to C , weighted with arclength ds , and summed around the curve C .

So... take a small disc D_ϵ of

radius $\epsilon > 0$, oriented with normal \vec{n} , placed at a point $\vec{x} = (x, y, z)$.

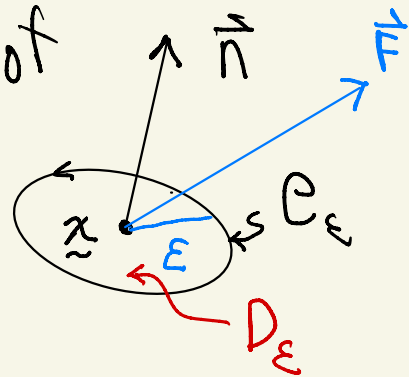
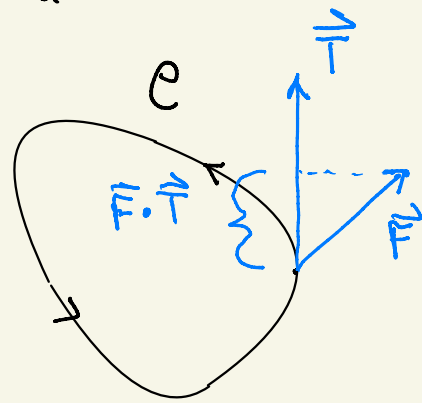
Let C_ϵ be the boundary circle of D_ϵ , oriented by RHR with \vec{n} .

Now apply Stokes Theorem:

$$\iint_{D_\epsilon} \text{Curl } \vec{F} \cdot \vec{n} \, dS = \oint_{C_\epsilon} \vec{F} \cdot \vec{T} \, ds$$

We wonder what $\text{Curl } \vec{F} \cdot \vec{n}$ measures

We know this is circulation in \vec{F} around C_ϵ



Now for the trick: assuming \vec{F} is smoothly varying, (say continuous derivatives) we know that as $\epsilon \rightarrow 0$, the value of $\text{Curl} \vec{F} \cdot \vec{n}$ in D_ϵ is very close, i.e. tends to its value at the center, namely, $\text{Curl} \vec{F} \cdot \vec{n}(\vec{x})$. Thus we can approximate $\text{Curl} \vec{F} \cdot \vec{n}$ as constant, and pull it out of \iint_{D_ϵ} , only incurring a small error which will be negligible as $\epsilon \rightarrow 0$.

I.e. $\iint_{D_\epsilon} \text{Curl} \vec{F} \cdot \vec{n} \, dS = \underbrace{\text{Curl} \vec{F} \cdot \vec{n}(\vec{x})}_{\substack{\text{what we are} \\ \text{trying to} \\ \text{interpret}}} \underbrace{\iint_{D_\epsilon} dS}_{\substack{\text{Area of } D_\epsilon = |D_\epsilon| = \pi\epsilon^2}} + \underbrace{\text{error}}_{\substack{\text{smaller than } |D_\epsilon|}}$

Thus from Stokes Theorem:

$$\iint_{D_\epsilon} \text{Curl} \vec{F} \cdot \vec{n} \, dS = \text{Curl} \vec{F} \cdot \vec{n}(\vec{x}) |D_\epsilon| + \text{error} = \oint_{C_\epsilon} \vec{F} \cdot \vec{T} \, ds$$

Divide thru by $|D_\epsilon| \dots$

$$\text{Curl} \vec{F} \cdot \vec{n}(\vec{x}) = \frac{1}{|D_\epsilon|} \oint_{C_\epsilon} \vec{F} \cdot \vec{T} \, ds - \frac{\text{error}}{|D_\epsilon|}$$

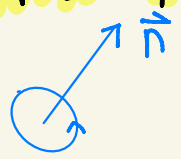
tends to zero as $\epsilon \rightarrow 0$

Thus: $\text{Curl}(\vec{F} \cdot \vec{n})(x) = \lim_{\epsilon \rightarrow 0} \frac{1}{|D_\epsilon|} \oint_{C_\epsilon} \vec{F} \cdot \vec{T} ds$

(Applies to any area D_ϵ oriented by normal \vec{n})

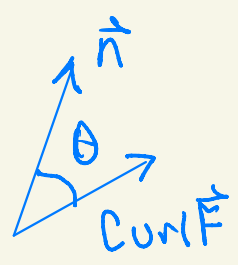
circulation per area

Conclude: The value of $\text{Curl}(\vec{F} \cdot \vec{n})$ at a point x measures the circulation per area in \vec{F} around the axis \vec{n} .



Example 3 Around which axis \vec{n} does \vec{F} exhibit maximum circulation?

Ans: $\text{Curl}(\vec{F} \cdot \vec{n}) = \|\text{Curl}(\vec{F})\| \|\vec{n}\| \cos \theta$



which is maximum when $\cos \theta = 1, \theta = 0$,

So the axis \vec{n} around which \vec{F} circulates most rapidly is $\vec{n} = \frac{\text{Curl}(\vec{F})}{\|\text{Curl}(\vec{F})\|}$, i.e. the direction of $\text{Curl}(\vec{F})$!

Example 4 What does the length of $\text{Curl } \vec{F}$ (6)

measure?

Ans: The maximum circulation per area occurs around axis $\vec{n} = \frac{\text{Curl } \vec{F}}{\|\text{Curl } \vec{F}\|}$, the magnitude being

$$\text{Curl } \vec{F} \cdot \vec{n} = \text{Curl } \vec{F} \cdot \frac{\text{Curl } \vec{F}}{\|\text{Curl } \vec{F}\|} = \frac{\|\text{Curl } \vec{F}\|^2}{\|\text{Curl } \vec{F}\|} = \|\text{Curl } \vec{F}\|$$

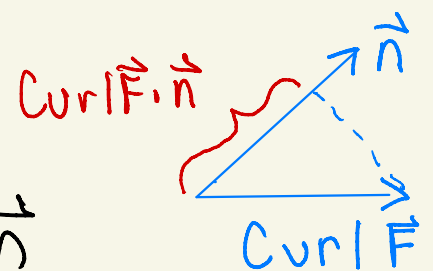
= maximum circulation per area

Conclude: $\text{Curl } \vec{F}$ gives the axis around which \vec{F} is circulating most rapidly, and its length is the magnitude of maximum circulation!

Note: The component of $\text{Curl } \vec{F}$ in any unit direction \vec{n} gives circulation per area around \vec{n}

$$\left(\text{Circulation per area around } \vec{n} \right) = \text{Curl } \vec{F} \cdot \vec{n} = \|\text{Curl } \vec{F}\| \cos \theta$$

= Component of $\text{Curl } \vec{F}$ in direction of unit vector \vec{n}

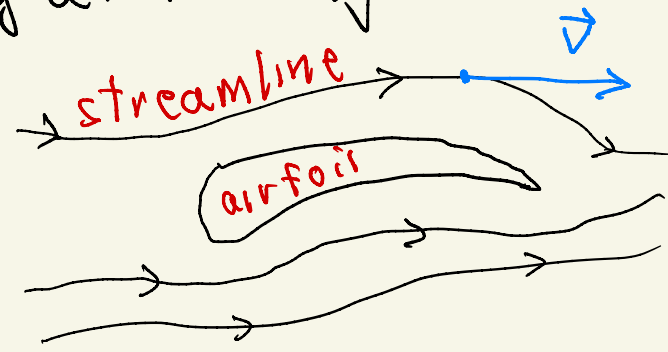


Application: The curl as "revolutions per second" = frequency in fluid model -

(7)

Assume $\vec{F} = \vec{v}$ = velocity in fluid model of a density $\delta(x, y, z)$ moving at velocity $\vec{v} = \vec{v}(x, y, z, t)$

I.e. a streamline $\vec{r}(t)$ is the curve taken by a fluid particle, and the velocity



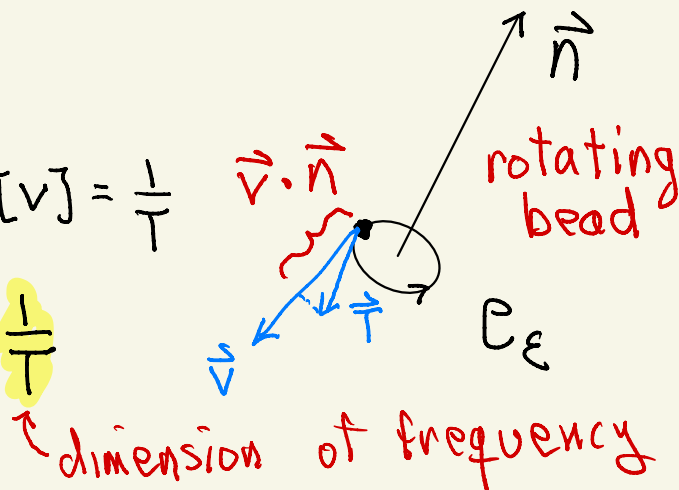
vector $\vec{v}(\vec{x}) = \vec{r}'(t)$ for the streamline thru $\vec{x} = (x, y, z)$

Q: What does $\text{Curl } \vec{v}$ measure at pt (x, y, z) ?

Ans: $\text{Curl } \vec{v} \cdot \vec{n} = 4\pi\omega$ where $\omega = \frac{\text{revolutions}}{\text{sec}}$ of a bead circulating on a circular wire C_ϵ oriented by \vec{n} assuming $\vec{v} \cdot \vec{T}$ gives the velocity (i.e., no friction, no loss of momentum) in limit $\epsilon \rightarrow 0$.

Check: Dimensions $[v_x] = \frac{1}{L} [v] = \frac{1}{T}$

$$[\text{Curl } \vec{v} \cdot \vec{n}] = \underbrace{[\text{Curl } \vec{v}]}_{\frac{1}{L} \frac{1}{T}} [\vec{n}]_1 = \frac{1}{T}$$



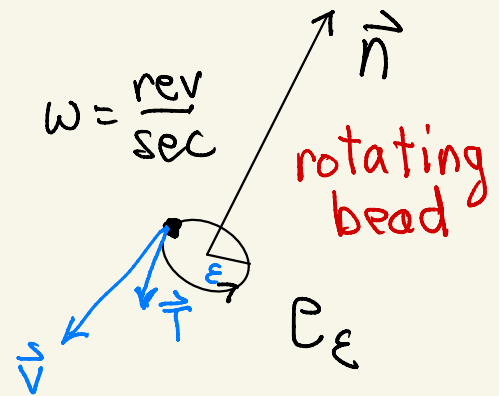
$\left(\frac{[\vec{n}]}{\|\vec{n}\|} \right) = \frac{[\omega]}{[\|\vec{n}\|]} = 1 \Rightarrow$ unit vectors are dimensionless

Example (5): Verify $\text{Curl } \vec{v} \cdot \vec{n} = 4\pi\omega$ (8)

Soln: $\text{Curl } \vec{v} \cdot \vec{n} \stackrel{\text{Stokes}}{\approx} \frac{\text{Circulation}}{\text{area}}$

$$= \frac{1}{\pi \epsilon^2} \int_{C_\epsilon} \vec{v} \cdot \vec{T} ds$$

$\underbrace{\hspace{10em}}_{\text{area}}$



(The approximate equality \approx becomes $=$ in limit $\epsilon \rightarrow 0$)

But

$$\int_{C_\epsilon} \vec{v} \cdot \vec{T} ds = \int_0^{2\pi} \vec{v} \cdot \vec{T} \epsilon d\theta$$

$$\vec{v} \cdot \vec{T} = \frac{ds}{dt}$$

= $\frac{\text{dist}}{\text{time}}$ of bead around C_ϵ

$$= 2\pi\epsilon \underbrace{\frac{1}{2\pi} \int_0^{2\pi} \vec{v} \cdot \vec{T}(\theta) d\theta}_{\bar{v} = \text{average speed } \frac{ds}{dt}}$$

$$= 2\pi\epsilon \bar{v}$$

Check:

$$\frac{1}{b-a} \int_a^b f(t) dt = \frac{1}{N\Delta t} \lim_{N \rightarrow \infty} \sum_{k=1}^N f(t_k) \Delta t_k = \lim_{N \rightarrow \infty} \underbrace{\frac{\sum_{k=1}^N f(t_k)}{N}}_{\text{average of } f}$$

Conclude: $\text{Curl } \vec{v} \cdot \vec{n} \approx \frac{1}{\pi \epsilon^2} 2\pi \epsilon \bar{v} = \frac{2}{\epsilon} \bar{v}$ (9)

Now: at average speed \bar{v} , the bead makes one revolution around $2\pi \epsilon =$ circumference of \mathcal{C}_ϵ in time period T where

$$2\pi \epsilon = \bar{v} \cdot T \Rightarrow T = \frac{2\pi \epsilon}{\bar{v}}$$

$\text{dist} = \frac{\text{dist}}{\text{time}} \cdot \text{time}$

Thus: $\frac{\# \text{ rev}}{\text{sec}} = \frac{1}{\text{time of one rev}} = \frac{1}{T} = \frac{\bar{v}}{2\pi \epsilon} = \omega$

Conclude:

$$\omega = \frac{\bar{v}}{2\pi \epsilon}, \quad \text{Curl } \vec{v} \cdot \vec{n} = \frac{2}{\epsilon} \bar{v}$$

$$\bar{v} = 2\pi \epsilon \omega \Rightarrow \text{Curl } \vec{v} \cdot \vec{n} = \frac{2}{\epsilon} 2\pi \epsilon \omega = 4\pi \omega \quad \checkmark$$

Summary: In the fluid model, the $\text{Curl } \vec{v}$ gives axis of maximal rotation of a bead constrained to move around a circular wire oriented \perp $\text{Curl } \vec{v}$. The length $\|\text{Curl } \vec{v}\|$ then gives the maximal frequency of rotation, and $\text{Curl } \vec{v} \cdot \vec{n}$ gives frequency of rotation around axis \vec{n} .

In Fluid Mechanics: $\text{Curl } \vec{v} = \text{vorticity}$. Vorticity plays a fundamental role in the theory of fluids.

Example (6) Assume a fluid is moving with velocity vector $\vec{F} = \vec{V} = x\hat{i} + xyz\hat{k} \frac{m}{s}$ ($\frac{m}{s} = \frac{\text{meters}}{\text{sec}}$)

- (1) Find axis of maximal rotation at $P = (1, -1, 2) = \underline{x}_0$
- (2) Find the maximal circulation/area
- (3) Find the frequency ω and period T for a bead rotating with \vec{V} around a circle of radius ϵ , center \underline{x}_0 , around axis $\vec{A} = (2, -1, 1)$.

Soln (1)

$$\text{Curl } \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \partial_x & \partial_y & \partial_z \\ x & 0 & xyz \end{vmatrix} = \hat{i}(xz-0) - \hat{j}(yz-0) + \hat{k}(0-0)$$

$$= xz\hat{i} - yz\hat{j}$$

$$\text{Curl } \vec{F} = \overrightarrow{(xz, -yz, 0)}$$

@ $\underline{x}_0 = (1, -1, 2)$, $\text{Curl } \vec{F} = \overrightarrow{(2, 2, 0)}$

∴ axis of max' rotation $\vec{n} = \frac{\text{Curl } \vec{F}}{\|\text{Curl } \vec{F}\|} = \frac{\overrightarrow{(2, 2, 0)}}{\sqrt{4+4+0}} = \frac{\overrightarrow{(1, 1, 0)}}{\sqrt{2}}$

(2) Maximal Circulation per area = $\|\text{Curl } \vec{F}\| = \sqrt{8} = 2\sqrt{2}$
 occurs around axis $\vec{n} = \frac{\overrightarrow{(1, 1, 0)}}{\sqrt{2}}$

(3) For $\vec{F} = \vec{V} \frac{m}{s}$, $\text{Curl } \vec{V} = \overrightarrow{(xz, -yz, 0)}$, $\text{Curl } \vec{V} \cdot \vec{n} = 4\pi\omega$

$$\omega = \frac{1}{4\pi} \text{Curl } \vec{V} \cdot \vec{n}(\underline{x}_0) = \frac{1}{4\pi} \overrightarrow{(2, 2, 0)} \cdot \frac{\vec{A}}{\|\vec{A}\|} = \frac{1}{4\pi} \frac{\overrightarrow{(2, 2, 0)} \cdot \overrightarrow{(2, -1, 1)}}{\sqrt{4+1+1}} = \frac{2}{4\pi\sqrt{6}} = \frac{1}{\sqrt{6}\pi}$$

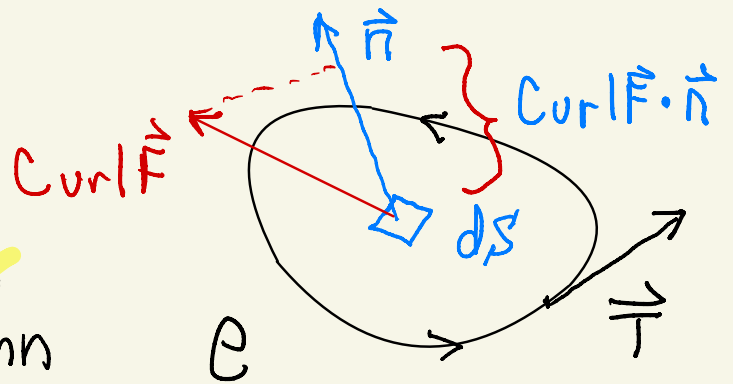
Ans: $\omega = \frac{1}{\sqrt{6}\pi} \frac{1}{\text{Sec}}$, $T = \frac{1}{\omega} = \sqrt{6}\pi$ Seconds

Why Stokes Theorem is true -

Stokes Theorem: $\iint_S \text{Curl } \vec{F} \cdot \vec{n} \, dS = \oint_C \vec{F} \cdot \vec{T} \, ds$

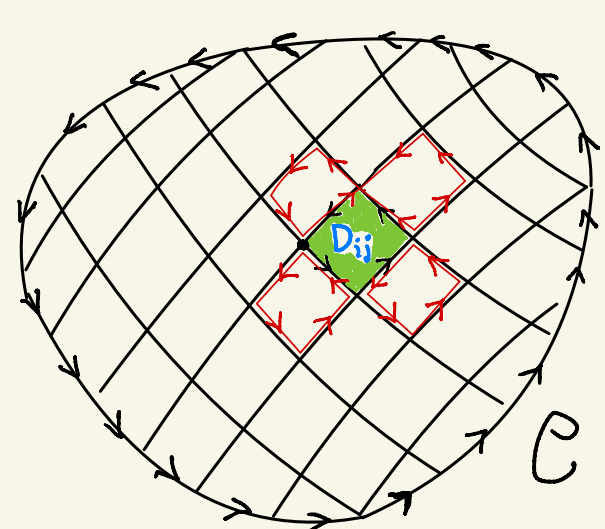
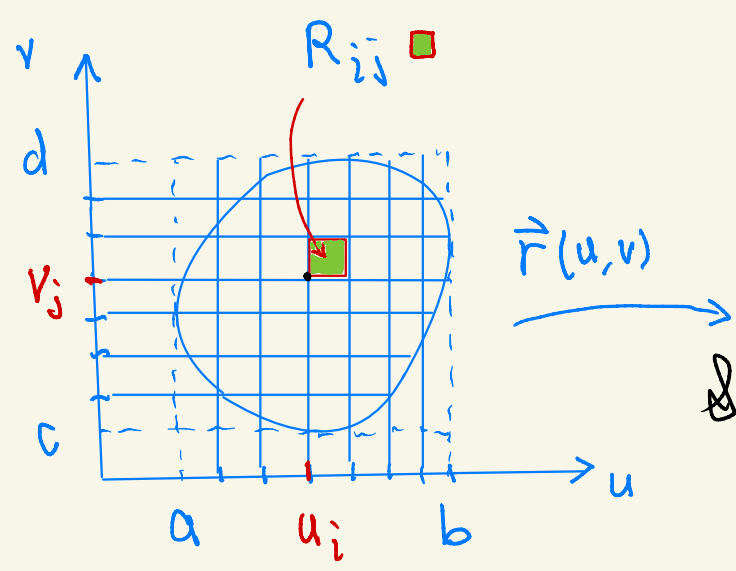
Q: Why is it true?

Ans: Because $\text{Curl } \vec{F} \cdot \vec{n}$ is the circulation per area, so when we write a Riemann sum for $\iint_S \text{Curl } \vec{F} \cdot \vec{n} \, dS$, each element D_{ij} reduces to a line integral around its boundary, and all the interior adjacent line integrals cancel out because they have opposite orientation.



I.e., $\iint_S \text{Curl } \vec{F} \cdot \vec{n} \, dS = \lim_{N \rightarrow \infty} \left| \sum_{ij} \iint_{D_{ij}} \text{Curl } \vec{F} \cdot \vec{n} \, dS = \sum_{ij} \int_{C_{ij}} \vec{F} \cdot \vec{T} \, ds \right|$

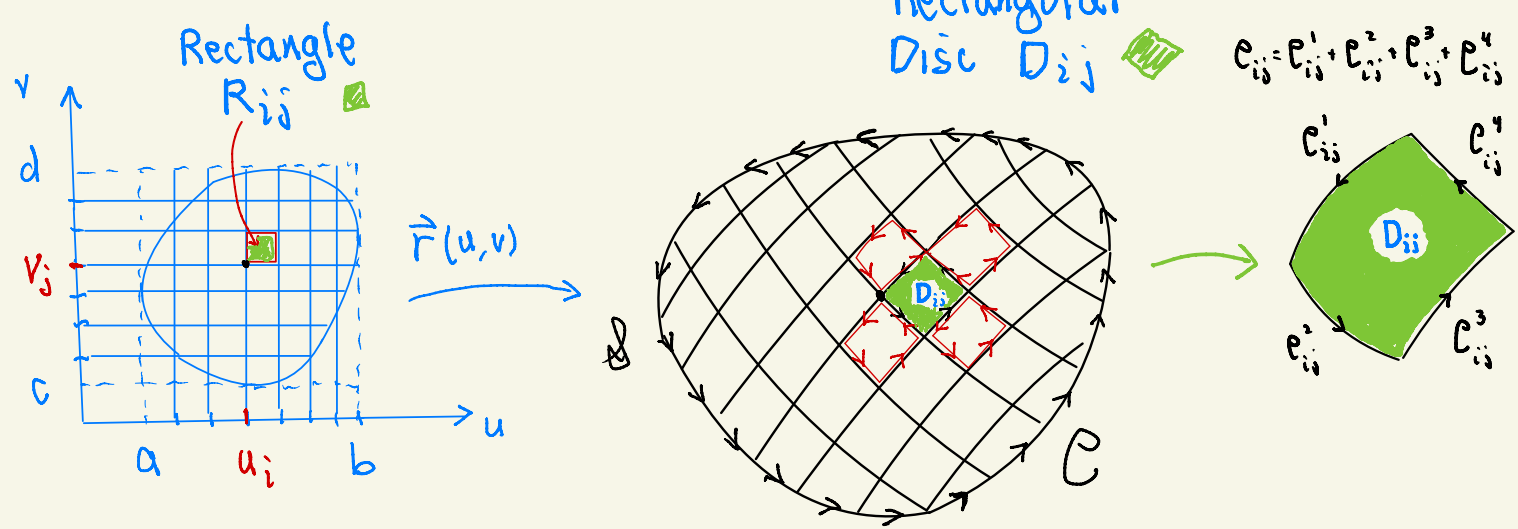
$= \int_C \vec{F} \cdot \vec{T} \, ds$



I.e., $\iint_{\Delta} \text{Curl} \vec{F} \cdot \vec{n} \, dS = \lim_{N \rightarrow \infty} \sum_{ij} \iint_{D_{ij}} \underbrace{\text{Curl} \vec{F} \cdot \vec{n}}_{\frac{1}{|D_{ij}|} \int_{C_{ij}} \vec{F} \cdot \vec{T} \, ds} \, dS$ $|D_{ij}|$

$= \lim_{N \rightarrow \infty} \sum_{ij} \int_{C_{ij}} \vec{F} \cdot \vec{T} \, ds$ All adjacent line integrals cancel out leaving only boundary

$= \int_{\partial \Delta} \vec{F} \cdot \vec{T} \, ds$



That is; all integrals on adjacent sides cancel out because they have opposite orientation, and the only line integrals left are the line integrals around outer boundary.

Note: This would be a proof, except we used Stokes Theorem to get $\iint_{\Delta_{ij}} \text{Curl} \vec{F} \cdot \vec{n} \, dS = \int_{C_{ij}} \vec{F} \cdot \vec{T} \, ds$, so we can't formally use that to prove Stokes Thm.

Conclude: The argument is circular in the sense that we assume Stokes Thm to interpret $\text{Curl } \vec{F} \cdot \vec{n}$ as circulation per area, then use this to prove Stokes Thm - Even so, this is the correct intuition for why Stokes Thm is TRUE! \circ